Rotary encoder connection and setup

There are 2 types of rotary encoders widely used in pendants and operator panels:

• Simple rotary encoder based on 2 switches. This type of encoders usually generates around 10-40 pulses per revolution (PPR) and used as fancy style "endless multi-turn potentiometer".



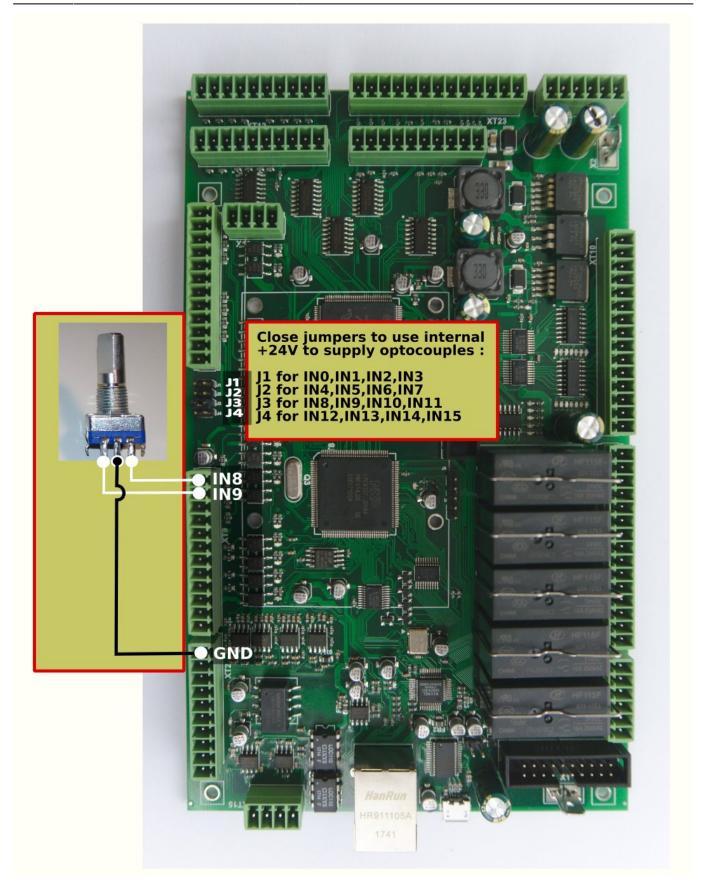
• Industrial style MPG with 100ppr and line driver 5V output

Both types can be connected to myCNC controller and used the operator control panel.

EN11 rotary encoder connection

Encoders can be connected to the galvanic isolated binary inputs. 2 Inputs are used to connect each encoder.

Last update: 2019/12/30 mycnc:rotary_encoder_connection_and_setup http://cnc42.com/mycnc/rotary_encoder_connection_and_setup?rev=1577724441 11:47



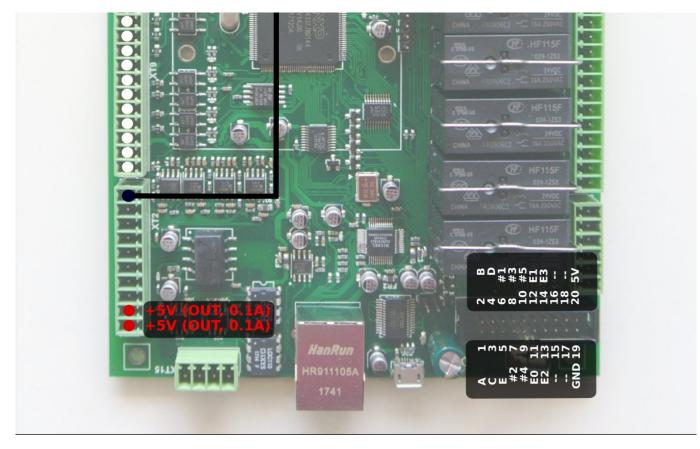
Encoder should be set up in the **Config > Inputs/Outputs/Sensors > MPG through binary inputs** configuration dialog.

myCNC controllers support up to 4 software encoders defined through binary inputs.

ET7 controller slow encoders setup

The myCNC-ET7 control board has 2 encoders (Encoder #0, #1) reserved defined permanently. These encoders are supposed to be installed on the ET7-KEY keyboard panel and connected to the 20-pin X4 connector on ET7 control board. It's possible to use external encoders without the ET7-key panel board and to connect those directly to X4 pins 11,12,13,14 and 19. See the table below for more information on the ET7 X4 pinout table:

X4 connector to External 25-keys keyboard		
Pin#	Name	Comments
11	E#0	Binary input #16, En#0 A
12	E#1	Binary input #17, En#0 B
13	E#2	Binary input #18, En#1 A
14	E#3	Binary input #19, En#1 B
19	GND	



These pins are actually Binary inputs #16, #17, #18, #19 which are permanently configured as Encoder#0 and Encoder#1 in myCNC-ET7 controller firmware. This is the reason Slow Encoders #0, #1 configuration for ET7 controller in myCNC software is ignored and can be skipped. **However, Encoder #2, Encoder#3 can be attached to any or binary inputs and configured accordingly when using the ET7 board.**

For all other control boards (ET6, ET10 and ET15), the slow encoders configurations #0-3 are active and can be used by users.

Rotary encoders setup example is shown on a picture below

1.47					
SYS PLC Log Config	Info Support Camera Config				S (
CNC Settings	MPG/Encoder through	binary inputs			
Axes/Motors Inputs/Outputs/Sensors	Input1 Input	Slot	Axis Dimensio	Encoder	
Alarms	input input	SIOU	AXIS DIMENSIO	Resolution	
X-Alarms	#0 🐹 16 🔶 17	🗘 MPG wheel 🔹	General Purpose 💌	400 🔶	
Limits	#1 🔀 18 🔶 19	+ MPG wheel -	General Purpose 🔻	400 ÷	
Triggers/Timers MPG through binary inputs					
Jog through ADC inputs		♣ MPG wheel ▼	Pendant 👻	65536 🜩	
I/O Expand cards mapping	#3 🗹 2 🔶 3	🗘 MPG wheel 🛛 💌	General Purpose 💌	400 ≑	
ADC Mapping	MPG/Encoder ET10 er	coder inputs			
Connections Network	Input#	Slot	Axis Dimensio	Encoder	
Motion	input#	5100	AXIS DIFFICISIO	Resolution	
PLC	#4 🗹 ET10 Encoder#2	▼ MPG wheel ▼	x -	100 🔶	
G-codes settings	#5 🗹 ET10 Encoder#4	▼ MPG wheel ▼	X •	100 🜲	
DXF import settings Macro List	#6 🔀 ET10 Encoder#0		x •		
Macro Wizard					
Probing Wizard	#7 🔀 ET10 Encoder#0	▼ MPG wheel ▼	X •	100 🔶	
Preferences					
 Screen Work Offsets 					
Parking Coordinates					
Technology					
Camera					
5 axes RTCP Panel/Pendant					
Hardware					
Advanced					

There are 2 encoders attached on Inputs #0,1,2,3 and set up in the dialog.

- Encoder #2 is attached to inputs #0 and #1 and used as a Pendant MPG/Wheel.
- Encoder #3 is attached to inputs #2 and #3 and used as a general purpose encoder.

For ET7 controller, Encoders #0 and #1 are connected to the X4 connector pins 11-14 (or through the ET7-KEY keyboard) and are configured despite being disabled in the myCNC settings window.

Encoder connection setup through configuration dialog.

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SYS PLC Log Config	Info Support Camera	Config				
CNC Settings	Source	Parameter D	estination Paran	neter K	ко	-
Axes/Motors	Jource		connucion i urun	inclui K		
 Inputs/Outputs/Sensors Alarms 	Encoder	v 1	Item 🔻	cnc-gvariable-7011	0.5	
X-Alarms	Encoder	- 2	Item 🔹	motion-overspeed		
Limits	· · · · · · · · · · · · · · · · · · ·			modon overspeed		
Triggers/Timers		-				
MPG through binary inputs						
Jog through ADC inputs						
I/O Expand cards mapping ADC Mapping						
Connections						
Network						
Motion						
▶ PLC						
G-codes settings						
DXF import settings Macro List						
Macro List Macro Wizard						
 Probing Wizard 						
 Preferences 						
Screen						
Work Offsets						
Parking Coordinates						
 Technology Camera 						
5 axes RTCP						
 Panel/Pendant 						
▶ Hardware						
Advanced						

A general purpose encoder can be connected to one of the system variables for convenient control.

There is a configuration dialog (described further in the MyCNC Configuration Dialogs manual) which can be used to set up a connection between slow encoder values and CNC parameters.

- Source a source of connection can be an Encoder, ADC, input/output pin, PWM, a global variable or other parameters
- Source/Parameter address of the source. It can be Encoder number, input pin number, global variable address etc
- Destination destination connection
- Destination/Parameter destination address
- K destination ratio. For example, Spindle speed will be increased 100RPM every encoder clicks if "K=100".
- K0 destination shift ratio. Usually left to be at 0 (field left to be blank).

On-panel rotary encoders are mostly used to control the following values on-the-fly:

- Overspeed [%] (5-150% safe range)
- THC Arc reference voltage [V] (actually cutting height)
- Spindle speed

A rotary encoder should be connected to the XML configuration Item "motion-overspeed" to control Overspeed [%]

Global variable register 7011 is used to change on-the-fly Cutting height (THC Arc reference voltage)

To change Spindle speed, the XML Item "spindle-default-speed" can be used.

SYS PLC Log Config	Info Support Camera Config				SAVE CFG
CNC Settings Axes/Motors Inputs/Outputs/Sensors Alarms X-Alarms Limits Triggers/Timers MPG through binary inputs Jog through ADC inputs I/O Expand cards mapping ADC Mapping Connections Network Motion PLC G-codes settings DXF import settings Macro List Macro Wizard Probing Wizard Probing Wizard Probing Wizard Proferences Screen Work Offsets Parking Coordinates Technology Camera S axes RTCP P Anel/Pendant Hardware Advanced	Source Parameter Encoder 1 Encoder 2	Destination Po	rrameter K cnc-gvariable-7011 motion-overspeed	KO	-

A further selection of commonly used Items can be found in the Common Item List manual.

Obsolete method to establish connection through "cnc-variables.xml" configuration file.

This method was used before the dialog described above was released. Only used on the old deprecated software versions

The connection assignment can be written directly in the cnc-variables.xml configuration file. For example:

```
<value name="cnc-connection-item-002"
source="encoder:3"
dest="item:motion-overspeed" >0</value>
```

- source="encoder:3" encoder #3 defined as a source
- dest="item:motion-overspeed" motion-overspeed defined as destination

Encoder #3 connected to **motion-overspeed** variable. Overspeed (%) value will be changed by rotating the encoder.

```
<value name="cnc-connection-item-003"
source="encoder:2"
dest="item:cnc-gvariable-7012">0</value>
```

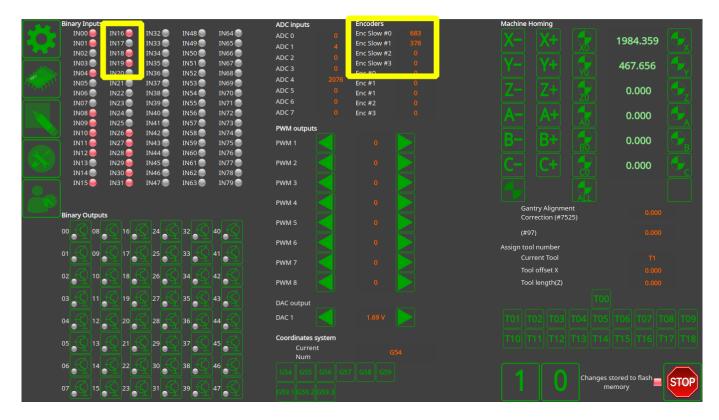
- source="encoder:2" encoder #2 defined as a source
- dest="item:cnc-gvariable-7012" Global variable for THC Arc Voltage Adjustment value is a

destination for the connection

Encoder #2 is connected to the THC Arc voltage adjustment. Adjustment Arc value will be changed to +1" or -1" on every encoder click.

Encoder connection troubleshooting

- Go to the Diagnostics page in myCNC software and check which binary input pins the encoder is attached to. To do so, monitor the binary inputs section of the Diagnostics page as you turn the encoder - the relevant input pins should blink as the encoder dial is moved. The input pins #18 and #19 are used in this example, as can be seen in the following picture:
- 2. Check that the "Slow Encoder" values are changed while you turn the encoder.
- 3. Check that the Destination item value has changed while you turn the encoder.
- 4. After the checkup has been complete, reload the program to refresh the settings to the newest configuration.





Video

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Last update: 2019/12/30 11:47

